

(above) Original Commands

Original commands plus weight:



New commands plus weight:



New commands without added weight:



Proportional control with original k value:



Original k plus weight:



New k value plus weight:



New k value without added weight:



Better control (step 7) with original k and Ki values:



Step 7 with original values plus weight (an extra motor):



Step 7 new values plus weight:



Step 7 new values no added weight:

